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# Estimation of the minimum fluidisation velocities in well-mixed bi-disperse fluidised beds

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## Abstract

A method for estimating minimum fluidisation velocities in a well-mixed, bi-disperse fluidised bed of spherical particles is described where a drag model is combined with a particle packing model. The method described does not require empirical input about a specific particle mixture, and so these minimum fluidisation velocities can be estimated over wide ranges of size and density ratios. The treatment is fully non-dimensionalised. It is shown that two minimum fluidisation velocities may be defined for a well mixed bi-disperse bed: the gas speed at which fluidisation initiates determined from considering the bed as a whole, and a higher one corresponding to the balance of forces on an individual particle. The differences between bi- and mono-disperse beds are the change in particle volume fraction owing to packing, the difference in drag around individual particles compared with the average drag, and the action of the hydrostatic pressure gradient. The latter two effects tend to increase the difference between the two limits of minimum fluidisation velocity, while packing decreases it and intensifies the dependence on mass fraction of the minimum fluidisation velocities. The influence of inertia is determined from particle properties through an Archimedes number. Though the inertial effects are not large for a wide range of particles, they can start to dominate other influences on the minimum fluidisation velocities as particle diameter increases.

*Keywords:* fluidisation, minimum fluidisation velocity, bi-disperse

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## 1. Introduction

There is a long history of interest in the minimum fluidisation velocity,  $u_{mf}$  for when a bed consists of two well-mixed sets of particles of different densities and sizes. This has been of particular recent interest because of its relevance to biomass combustion and gasification where relatively large and light biomass particles must be well-mixed with inert material particles and the bed must be fully fluidised [1]. Classical approaches to estimating the minimum fluidisation velocity in a bi-disperse bed is summarised by [2]. One approach has been to empirically fit to experimental data, for example, Cheung *et al.*[3]. Another approach has been to calculate the minimum fluidisation velocities for bi-disperse beds in the same manner as a mono-disperse bed with particle densities and diameters averaged in some manner to reflect the bi-disperse nature of the bed. For example, Goossens *et al.*[4] calculated the overall particle density and an average particle diameter that has the equivalent total surface area per unit weight. These quantities were then used in the Wen and Yu equation [5] to calculate  $u_{mf}$  as for mono-disperse fluidised beds. Subsequent developments of this method for specific applications have tried to improve correlations through adjustments to the numerical coefficients in the equation e.g. [6–8].

It became apparent that the estimation of the point of minimum fluidisation in bi-disperse beds is more complex than for mono-disperse beds beyond accounting for changes to the overall bed parameters. The estimated values of  $u_{mf}$  for a bi-disperse bed could vary from experimental measurements by as much as  $\pm 40\%$  [6, 7]. There are a number of issues that might account for this.

First, from measurements of pressure drop against velocity, it is apparent that in a bi-disperse bed fluidisation is not a single event that is the crossing of a threshold, but is a process that continues over a range of gas velocities [7, 9–11]. This results in the definition of two minimum fluidisation velocities, one at which fluidisation initiates and a higher one that corresponds to the gas speed at which the pressure drop over a bed reaches a maximum. This has been accounted for as a result of the segregation of particles above the initial minimum fluidisation velocity up to a gas speed above which the pattern of segregation becomes independent of gas speed.

The second issue that gives rise to uncertainty in estimating minimum flu-

34 idisation velocities is that when a bed consists of particles of different sizes, it is  
 35 possible for the smaller particles to pack the interstices between the large ones  
 36 [12, 13]. Drag is strongly dependent on particle volume fraction,  $\phi$ , which can  
 37 vary markedly with the degree of packing that the particle geometry allows and  
 38 the proportion of each of the bed components [9, 13]. There has been success  
 39 at estimating the initial minimum fluidisation velocity for bi-disperse beds by  
 40 measuring  $\phi$  directly and then calculating  $u_{mf}$  using the viscous term of the Er-  
 41 gun equation with mixture particle density and diameter [9, 14]. An alternative  
 42 approach has been to use curve fitting for empirical measurements of minimum  
 43 fluidisation velocity to account for the effect of packing [3, 13]. As well as  $\phi$ ,  
 44 the packing of small particles between the large ones will affect the nature of  
 45 the channels through which the fluidising gas passes through a bi-disperse bed  
 46 and hence the drag exerted on the particles [15].

47 A third issue is the exertion of hydrostatic forces as well as drag on particles  
 48 in a fluidised bed. This is straightforward to allow for in a mono-disperse bed,  
 49 but in a bi-disperse bed for which the densities of the two components are  
 50 different, the hydrostatic force on a particular particle depends on the proportion  
 51 of each component, and this can be difficult to account for [16].

52 In this paper, a method is presented for estimating minimum fluidisation  
 53 velocities in well-mixed bi-disperse fluidised beds of spherical particles that ex-  
 54 plicitly includes all their physical features without requiring empirical measure-  
 55 ments of a particular bed. A drag model [15, 17] is combined with the estimation  
 56 of  $\phi$  through the use of a packing model [18], and the effects of the hydrostatic  
 57 pressure gradient and inertia are included. The resulting equations are fully  
 58 non-dimensionalised, so the results are generally applicable. The model is ap-  
 59 plied at two scales: that of the overall bed, and that of the individual particle.  
 60 Several drag models are available, but that of Hoef *et al.* [15, 17] is used as it  
 61 allows the identification of specific physical mechanisms for the generation of  
 62 drag, and for drag to be calculated at both scales. This drag model has been  
 63 used successfully elsewhere to model fluidised beds e.g. [19–21]. The results  
 64 from this paper show the degree of complexity introduced into the process of  
 65 fluidisation by a second particle component.

## 66 2. Minimum fluidisation velocities in mono-sized fluidised beds

67 The minimum fluidisation velocity for a mono-sized bed of particles,  $u_{mf0}$ , is  
 68 the speed of a fluid flow through it,  $u_g$ , at which the particles' weight is matched  
 69 by the fluid forces acting upon them: drag and hydrostatic pressure. The drag  
 70 force can be written down as the Stokes drag on an isolated particle multiplied  
 71 by the factor  $F$  that accounts for the effect of surrounding particles and inertia  
 72 on the drag on a particle in a bed [17].  $F$  is a function of  $\phi_0$ , the particle volume  
 73 fraction for a mono-disperse bed, and  $Re$ , the particle Reynolds number. It can  
 74 be shown that the net force generated on a particle of diameter  $d_0$  when the  
 75 hydrostatic pressure gradient is taken into account is the drag force divided by  
 76  $1 - \phi_0$  [15]. When the bed is fully fluidised and the gas density is much less than  
 77 that of the particles,  $\rho_g \ll \rho_0$ , the force balance on a representative particle is

$$3\pi\mu d_0 u_g F + \phi_0 \rho_0 \frac{\pi}{6} d_0^3 g = \rho_0 \frac{\pi}{6} d_0^3 g, \quad (1)$$

78 where the first term is fluid drag and the third term is the weight of the particle.  
 79 The second term is the hydrostatic force exerted on the particles owing to the  
 80 suspension of the bed. [15].

81 In non-dimensional form [15]

$$\frac{F}{1 - \phi_0} u_{mf}^* = 1, \quad (2)$$

82 where

$$u_{mf}^* = u_{mf}/u_{t0}, \quad (3)$$

83 a type of Stokes number, and

$$u_{t0} = \frac{\rho_0 d_0^2 g}{18\mu} \quad (4)$$

84 is the terminal velocity of an isolated particle experiencing Stokes drag.

85 The correction  $F$  to the fluid drag can be divided into two parts, one viscous  
 86 and one inertial [17], so that

$$F = F_v(\phi) + F_{Re}(\phi, Re). \quad (5)$$

87 From the results of lattice Boltzmann simulations of flows through arrays of  
 88 particles, an expression for the low-Reynolds number correction  $F_v$  has been

proposed [15] and, for higher Reynolds numbers another for  $F_{Re}$  that has an accuracy of 10% when  $Re = 1000$  [17].

When a bed is viscously dominated, then  $u_{mf}^*$  is equal to a constant that is a function of  $\phi$  and information about a specific bed is introduced when scaling is removed. When inertia is significant then  $F$  is a function of  $Re$  as well as  $\phi$ .  $Re$  may be expressed as  $Re = Ar u_{mf}^*$  where

$$Ar_0 = \frac{\rho_g \rho_0 d_0^3 g}{18 \mu^2}, \quad (6)$$

is a Archimedes number describing the ratio between the weight of a particle and the viscous drag acting on it in a monodisperse bed when  $\rho_g \ll \rho_0$ . Eqn (2) can then be solved for  $u_{mf}^*$ . When viscous forces dominate then  $u_{mf}^*$  is a constant; when inertial forces are significant, then  $u_{mf}^*$  has to be found from the implicit solution of Eqn (2).

### 3. Minimum fluidisation velocities in well-mixed bi-disperse beds

For a bi-disperse mixture of particles,  $s$  will denote the ‘small’ diameter particles,  $l$  the ‘large’ diameter particles, and  $i$  denotes either component. The amount of small particles is denoted by the mass fraction  $x$ .

The average density for the bed is

$$\frac{1}{\rho_{av}} = \frac{x}{\rho_s} + \frac{1-x}{\rho_l}. \quad (7)$$

Two density ratios may be defined:

$$w = \frac{\rho_s}{\rho_l}; \quad z_i = \frac{\rho_i}{\rho_{av}}. \quad (8)$$

The Sauter diameter is a suitable average diameter [15],

$$\frac{1}{d_{av}} = \frac{x/z_s}{d_s} + \frac{(1-x)/z_l}{d_l}. \quad (9)$$

Two size ratios are defined as

$$r = \frac{d_s}{d_l}; \quad y_i = \frac{d_i}{d_{av}}. \quad (10)$$

All the particles in this article are assumed to have Geldart group-B behaviour i.e.  $\phi_0$  is independent of  $u_g$ .

### 110 3.1. Forces on a bed as a whole

111 For the whole bed, the minimum velocity at which fluidisation initiates may  
 112 be defined as that at which it ceases to act as a static bed,  $u_{mf1}$ . This will  
 113 be when the weight of the entire fixed bed of particles is just matched by the  
 114 fluid forces upon it [9, 12]. In a fixed bed, forces are transmitted directly from  
 115 one particle to another, and so the bed may be considered in bulk. The same  
 116 framework for expressing drag as for a mono-disperse bed of particles may be  
 117 employed with  $Re$  based on an average, representative particle so that in di-  
 118 mensionless terms, when the weight of the bed in bulk is fully supported by the  
 119 gas flow,

$$\left[ F_v(\phi) + F_{Re}(\phi, Ar_{av} u_{mf1}^*) \right] \frac{u_{mf1}^*}{1 - \phi} = 1. \quad (11)$$

120 where  $u_{mf1}^* = u_{mf1}/u_{tav}$  is the dimensionless minimum fluidisation velocity for  
 121 the whole bed.  $u_{tav}$  and  $Ar_{av}$  are based on  $d_{av}$  and  $\rho_{av}$ . This is the equivalent of  
 122 the expression for the initial minimum fluidisation velocity in [9], though there  
 123 the drag is based on the Carmen-Kozeny equation. As for Eqn (2), the  $\phi$  in the  
 124 denominator arises because of the hydrostatic force generated by the suspension  
 125 of all the particles.

### 126 3.2. Fluidisation based on forces on individual particles

127 In a well-mixed, bi-disperse bed not all of the particles will be fully fluidised  
 128 when  $u_{mf1}^*$  is exceeded. On one of the components the force exerted on a particle  
 129 will be more than that necessary to fluidise it, but on the other component it  
 130 will be less. When the particles are in contact, the excess force from the former  
 131 component can be transmitted to the latter; however, if a well-mixed bed is  
 132 to be fully fluidised, the particles should not be in sustained contact with each  
 133 other and each particle must be supported individually by the gas flow [22]. To  
 134 determine the gas velocity at which this takes place, the forces exerted by the  
 135 gas flow on an individual particle must be considered. This will define an upper  
 136 fluidisation velocity,  $u_{mf2}$ , expressing the minimum gas velocity for the weight  
 137 of the particle to be supported in a fully-fluidised, well-mixed bed.

138 The gas velocity at which an individual particle's weight is supported will  
 139 depend on its characteristics, not the average ones for the bed. There are

also two important differences between the forces on individual particles in bi-disperse beds and the force on an average particle.

First, when a bi-disperse system is considered at the bed-scale, the average non-dimensional drag on a particle is equivalent to the non-dimensional drag on a particle in a mono-disperse bed with the same  $\phi$ ; however, when an individual particle is considered, this is not true [15]. Through lattice-Boltzmann simulations, it has been shown that for bi-disperse beds of spherical particles, this may be expressed by multiplying  $F$  by a factor [15]

$$F_{pi} = ((1 - \phi) y_i + \phi y_i^2). \quad (12)$$

A better fit with simulation results can be found with the addition to Eqn (12) of  $0.064(1 - \phi) y_i^3$  [15]; however, this was at the expense of drag no longer taking on the values for mono-disperse beds when  $x = 0$  or  $x = 1$  [15] and the benefit is only significant for values of  $\phi$  much smaller than those found in dense fluidised beds [15].

The second difference is the action of the pressure gradient. In a bi-disperse bed, when individual particles are considered there is cross-coupling in the momentum balance for a particle as the total force acting on a particle of one-component will depend on the force exerted by the fluid on the particles of the other component. For a general description of bi-disperse particle systems, this is a difficult problem [16]; however, for a fully-fluidised bed, it can be overcome as the pressure gradient can be equated to the weight of particles in the whole bed so that it has the value  $-\phi \rho_{av} g$ . For particles of different sizes but equal densities in a fully-fluidised bed, the total force on a particle will be the drag force divided by  $(1 - \phi)$ , in a similar manner to mono-sized particles.

For a particle of component  $i$ , the velocity at which fluid forces equals the weight of an individual representative particle of component  $i$ ,  $u_{mf2i}$  in a bi-disperse bed is given by the force balance per unit weight for the particle,

$$F_{pi} (F_v + F_{Re}) \frac{u_{mf2i}}{u_{ti}} + \phi \frac{\rho_{av}}{\rho_i} = 1. \quad (13)$$

The first term on the left-hand side expresses drag, the second term is buoyancy, and the right-hand side is particle weight. Converting to non-dimensional variables and using Eqn (12),

$$u_{mf2i}^* = \frac{1}{F_v + F_{Re}} (z_i - \phi) \left( \frac{y_i}{(1 - \phi) + \phi y_i} \right) \quad (14)$$



169 or when viscous forces dominate, from Eqn (11)

$$u_{mf2i}^* = u_{mf1}^* \left( \frac{z_i - \phi}{1 - \phi} \right) \left( \frac{y_i}{(1 - \phi) + \phi y_i} \right). \quad (15)$$

170 The first term in brackets corresponds to the effect of buoyancy and the second  
171 term the effects of the difference between the diameter of the particle being  
172 considered and  $d_{av}$ .

173 *Characterising a bi-disperse fluidised bed with  $u_{mf2i}$*

174  $u_{mf2i}^*$  can be defined for a particle from either component of a bi-disperse  
175 mixed bed. Only will it have physical meaning when the entire bed is fully  
176 fluidised, otherwise the buoyancy term in Eqn (13) is incorrect; therefore, for  
177 a particular value of  $x$ , the larger value of  $u_{mf2i}^*$  characterises the minimum  
178 velocity at which a mixed fluidised bed is fully fluidised (denoted as  $u_{mf2}^*$ ); the  
179 value for the other component does not have physical meaning.

180 Which component defines  $u_{mf2i}^*$  depends on  $r$  and  $w$ , with the density ratio  
181 having the greater influence. When the larger component is also the denser  
182 ( $w < 1$ ),  $u_{mf2}^* = u_{mf2l}^*$  always. When the small particles are the denser ( $w > 1$ )  
183 then for any  $r$  there will be a limiting value of  $w$  below which the larger, less-  
184 dense particles may define  $u_{mf2}^*$  rather than the smaller, denser ones. The  
185 ranges over which this are true for when inertial effects are negligible is shown  
186 in Fig. 1. Even for very large differences in the diameters of the two components,  
187 the larger, less-dense particles define  $u_{mf2}^*$  only when  $x$  is small or when  $w$  is  
188 not much more than 1.

#### 189 4. Scaled results

190 For bi-disperse fluidised beds, two minimum fluidisation velocities may be  
191 found:  $u_{mf1}^*$  for when fluidisation initiates, and  $u_{mf2}^*$  for when a well-mixed,  
192 bi-disperse bed can be completely fluidised. Particle shape is not investigated  
193 here, so in a bi-disperse bed the particles may differ in size and density. The  
194 simplest case that can be used to examine the effects of these properties is  
195 when  $r$  is large so that  $\phi$  is not a function of  $x$  and a bi-disperse bed acts in  
196 a similar way to a mono-disperse bed. When the difference in size of particles  
197 is sufficiently large for  $\phi = f(x)$ , then the behaviour of the bed with respect

198 to the minimum fluidisation velocities changes. A further complication will  
 199 be the effect of inertial forces when they are large enough to be significant.  
 200 Each of these cases will be examined in turn and, through the use of scaled  
 201 parameters, for bi-disperse fluidised beds in general. There will then be an  
 202 example showing how the scaled parameters relate to unscaled velocities and  
 203 how the other factors described here affect minimum fluidisation velocity when  
 204 compared with the primary scaling found in mono-disperse fluidised beds.

#### 205 *4.1. Minimum fluidisation velocities in beds where $\phi$ is fixed and viscous drag* 206 *dominates*

207 For particles of a similar shape, when  $r > 0.741$  the mixture of two bed  
 208 components has the same particle volume fraction mixed as when they are  
 209 unmixed,  $\phi = \phi_0$  [23]. The minimum fluidisation velocities for these conditions  
 210 are shown in Fig. 2. Taken as a whole, such a bed is analogous to a mono-  
 211 disperse bed of particles with average properties so that when viscous forces  
 212 dominate,  $u_{mf1}^*$  has a fixed value given by Eqn (2), which has a value of 0.0106  
 213 when  $\phi = 0.60$ .  $u_{mf2}^*$  increases with  $x$  owing to the effect of the hydrostatic  
 214 pressure gradient.  $r = 1$  corresponds to the special case when bed components  
 215 have the same size, but different densities. When  $w > 1$  (i.e. the smaller particles  
 216 are also the denser), a similar result to that shown in Fig. 2 is obtained except  
 217 that the line describing  $u_{mf2}^*$  is reversed.

#### 218 *4.2. The effect of particle packing*

219 When  $r < 0.741$ , small, spherical particles can pack the interstices between  
 220 the large particles in a bi-disperse bed and  $\phi = \phi(x)$  and can be significantly  
 221 larger than  $\phi_0$  [23]. This can greatly affect the values of the scaled minimum  
 222 fluidisation velocities.

223 Packing behaviour in bi-disperse beds can be estimated without the use of  
 224 empirical measurements of specific mixtures of particles through the use of a  
 225 packing model. The linear-mixture model [18] combines a linear model [24] for  
 226 when  $r < 0.154$ , the point at which small spherical particles can move through  
 227 the interstices of large ones without disturbing them, with a mixture model [25]  
 228 for when  $0.154 < r < 0.741$ . The mixture model is appropriate when the values  
 229 of  $\phi_0$  for each component are equal, but if the particles for each component have

different shapes then a fully linear model must be used instead [18]. This model has been experimentally validated [18, 23, 25].

Mixture particle volume fractions depend on the partial volume fraction of the small particles  $X$  where

$$X = \frac{x}{x + w(1 - x)}. \quad (16)$$

For a binary mixture of spherical particles when  $\phi_{0s} = \phi_{0l} = \phi_0$ , when  $r \geq 0.741$ , then  $\phi = \phi_0$ . When  $0.154 \leq r < 0.741$ , then the particle volume fraction is determined by mixing and [24]

$$1/\phi = 1/\phi_0 + (1 - X)X(\beta + \gamma(1 - 2X)) \quad (17)$$

where

$$\beta = 10.288 \times 10^{-1.4566\phi_0} (-1.002 + 0.1126r + 5.8455r^2 - 7.9488r^3 + 3.1222r^4) \quad (18)$$

$$\gamma = (-1.3092 + 15.039\phi_0 - 37.453\phi_0^2 + 40.869\phi_0^3 - 17.11\phi_0^4) (-1.0029 + 0.3589r + 10.970r^2 - 22.197r^3 + 12.434r^4). \quad (19)$$

When  $r < 0.154$  then the particle volume fraction is dominated by unmixing. An overall particle volume fraction can be calculated [26] for both components and the lower value is taken to represent the mixture where

$$\phi_0/\phi_l = (1 - X) + (1 - f(r))X; \quad (20)$$

$$\phi_0/\phi_s = X + (1 - (1 - \phi_0)g(r))(1 - X), \quad (21)$$

where the interaction coefficients are given by

$$f(r) = (1 - r)^{3.3} + 2.8r(1 - r)^{2.7} \quad (22)$$

$$g(r) = (1 - r)^{2.0} + 0.4r(1 - r)^{3.7}. \quad (23)$$

The inset for Fig. 3a shows the computed increase in  $\phi$  for the values of  $r$  examined.

$$(24)$$

239

$$(25)$$

240 The effect of the packing of small particles between the large ones is shown  
 241 in Fig. 3a where  $w = 1$  i.e. the bed is a mixture of particles of two different  
 242 sizes, but the same density. There are two main effects of  $r$  on the values of  
 243 the two minimum fluidisation velocities. First,  $u_{mf1}^* \neq u_{mf2}^*$  and the difference  
 244 between the two scaled minimum fluidisation velocities increases with  $x$ , driven  
 245 by the difference between  $d_l$  and  $d_{av}$ . The second effect is that the shape of  
 246 the scaled minimum fluidisation curves is substantially changed by the increase  
 247 in the value of  $\phi$  when  $r < 0.741$  and decreases.  $u_{mf1}^*$  is no longer a constant,  
 248 but has a minimum whose value and the corresponding value of  $x$  decrease as  
 249  $r$  is reduced. When  $r$  is small, the effects of packing are dominant so that the  
 250 dependence on  $x$  of  $u_{mf2}^*$  is changed from a consistent rise to being pulled down  
 251 close to the line for  $u_{mf1}^*$ .

252 Fig. 3b shows the fluidisation curves when  $w = 0.5$  i.e. the larger particles  
 253 are also denser. The strong divergence between  $u_{mf1}^*$  and  $u_{mf2}^*$  with increasing  
 254  $x$  caused by the hydrostatic gradient (as seen in Fig. 2) is superimposed on the  
 255 shape of the curves generated by packing shown in Fig. 3a.

256 Fig. 3c shows the fluidisation curves when the smaller particles are more  
 257 dense than the larger ones ( $w > 1$ ). The dependence of hydrostatic pressure on  
 258  $x$  is simply reversed; however, the effects of packing are not, which results in  
 259 very different dependencies of the scaled minimum fluidisation velocities on  $x$ .  
 260 When  $w > 1$ , it is possible for  $u_{mf2}^*$  to be defined by the less-dense component,  
 261 but particle packing restricts this effect as shown in Fig. 1.

262 In Fig. 3a the value of  $u_{mf2}^*$  does not converge on the value of  $u_{mf_s}^*$  when  
 263  $x = 1$ . This is because  $u_{mf2}^* = u_{mf2l}^*$  so that the limiting case as  $x \rightarrow 1$  is of a  
 264 single large particle in a bed of small particles. From Eqn (15), the fluid force  
 265 required to suspend a large particle will exceed that for the small particles and  
 266 so  $u_{mf2}^* > u_{mf_s}^* = u_{mf1}^*(x = 1)$ . The same is true for Fig. 3b; however, for  
 267 Fig. 3c,  $u_{mf2}^* = u_{mf2s}^*$ , and so when  $x = 0$ ,  $u_{mf2}^* > u_{mf_l}^* = u_{mf1}^*(x = 0)$ .

### 268 4.3. The effect of inertial forces

269 Inertia has the effect of increasing the scaled drag experienced by particles  
 270 and reducing the scaled minimum fluidisation velocities. When the bed is con-  
 271 sidered as a whole and  $u_{mf1}^*$  is calculated, the same framework as for a mon-  
 272 odisperse bed may be employed with the effect of inertia characterised by the

Archimedes number  $Ar_{av}$  (defined by Eqn (6)) based on the average particle density and diameter. Its influence on  $u_{mf1}^*$  for a bi-disperse mixture where  $\phi = \phi_0$  is shown in Fig. 4. The value of  $u_{mf1}^*$  begins to significantly deviate from the value for when inertia is negligible when  $Ar_{av}$  has a value of a few hundred. For an idea of a physical meaning of the value of the Archimedes number,  $Ar = 500$  for glass particles ( $\rho_p = 2500 \text{ kg/m}^3$ ) fluidised by air when  $d_p = 445 \mu\text{m}$ .

$Ar_{av}$  is based on the average particle diameter quantities and so for most cases diminishes as  $x$  becomes larger. This means that even in beds where the larger component is large and heavy, inertial forces may not be significant over large ranges of  $x$  when  $w$  is small. The dependency of  $Ar_{av}$  on  $d_{av}$  means that it is no longer possible to plot a completely general variation of the minimum fluidisation velocities with  $x$ . Fig. 5 shows the variation of the minimum fluidisation velocities with  $x$  for several values of  $r$  for a value of  $Ar_s$  selected so that inertia is always important, even at high  $x$ . Comparison with Fig. 3c shows that the effect of inertial forces is to increase drag, particularly at low  $x$  and to reduce the effects of packing on the minimum fluidisation velocities.

## 5. Unscaled results

It has been shown above that in bi-disperse fluidised beds, it is possible for  $r$  and  $w$  to cause significant variation from the values of the scaled minimum fluidisation velocity that would be expected from considering equivalent single-component fluidised beds. However, the dominant scaling in fluidised beds is between the weight and the fluid forces acting upon a particle, and in a bi-disperse bed this is expressed by  $u_g/u_{tav}$ . Figure 6 compares the scaled and unscaled minimum fluidisation velocities for the particles whose properties are summarised in Tab. 1. The principle scaling in a fluidised bed between weight and drag is evident. When a bi-disperse fluidised bed behaves as a single-component fluidised bed, then from Eqns (2) and (4), the minimum fluidisation velocity is inversely proportional to  $\rho_{av}d_{av}^2$ , which gives rise to an exponential decrease in minimum fluidisation velocities with  $x$ . When  $r$  is small, then increased packing very much intensifies the variation with  $x$ . The result is a very steep drop in minimum fluidisation velocities with  $x$  and which then have nearly

constant values over large ranges of the higher values of  $x$ .

## 6. Discussion and conclusion

The method for estimating minimum fluidisation velocities in well-mixed, bi-disperse fluidised beds of spherical particles described here does not require any empirical measurements for a particular bed. The equations are also non-dimensionalised and so are applicable to any bed for which the constituent models may be applied.

There are two scales that may be considered for a fluidised bed: the overall bed scale and that of individual particles. In a mono-sized bed these two scales can be reconciled in that it is the point of minimum fluidisation is considered to be the point at which the forces on all of the individual particles balance and this is manifest at the bed-scale by the pressure drop over the bed reaching a maximum with respect to gas speed. For the whole-bed scale, the minimum fluidisation velocity  $u_{mf1}$  is the initial minimum fluidisation velocity that has been defined previously e.g. [3, 10, 27]. The results for  $u_{mf1}$  compare well with classical predictions of the minimum fluidisation velocity for large  $r$  when there is no packing of the small particles between the large ones, as shown in figure 7a. When  $r$  is small, Figs 7b and 7c, the packing of the particles has a significant effect on the expected values of  $u_{mf1}$ , resulting in significant deviations. The correlation of Noda *et al.* [6] was developed specifically for beds with a small value of  $r$ , but does not appear to offer great advantages over the simpler correlations. The packing model can be adapted to allow for more than two components and also differently shaped particles [18], but the degree of the challenge of this is shown by the predictions of a correlation that was developed specifically for beds containing biomass particles, which are also likely to be segregating strongly [8]. Though it was able to estimate the minimum fluidisation velocities for the specific situation that it was developed for, it deviates a great deal from other drag-model based predictions not specifically prepared for biomass systems.

In a well-mixed bi-disperse bed, the bed-scale minimum fluidisation velocity does not correspond to the gas speed at which the forces on an individual particle balance because it is determined by the balance of forces on the particle, includ-

337 ing buoyancy, which is determined by the density ratio, and a factor accounting  
 338 for the difference between drag on an individual particles and the average drag,  
 339 determined by the size ratio. This gives rise to a higher fluidisation velocity,  
 340  $u_{mf2}$ . This is different from the final minimum fluidisation velocity defined  
 341 previously e.g. [3, 10, 27], which describes the higher gas velocity that would  
 342 enable segregation to fully take place and the bed to become steady state:  $u_{mf2}$   
 343 applies to a well-mixed bed and so is not associated with segregation nor with  
 344 the bed being in a transient state. This is likely to be particularly important in  
 345 applications for which  $x$  is large, such as biomass combustion and gasification  
 346 where a bed may appear to fluidised as a whole, but individual particles may  
 347 not be.

348 The point at which the weight of all the particles in most practical bi-disperse  
 349 beds is supported is difficult to predict because of the propensity for many beds  
 350 to segregate. Many forms of segregation have been observed, and bi-disperse  
 351 beds can segregate into regions containing different proportions of the two bed  
 352 components e.g. [28]. The propensity of fluidised beds to segregate readily is  
 353 explained by the fact that even in well-mixed beds, there is a region between  
 354  $u_{mf1}$  and  $u_{mf2}$  where the bed is no longer static as a whole, but the different  
 355 magnitudes of the forces acting on particles in each component can cause se-  
 356 gregation [20, 22]. The overall segregation pattern will depend on the balance  
 357 between mixing and segregation processes within a specific bed [29]. Further-  
 358 more, segregation takes place on a different scales, and small scale regions of  
 359 different composition to their surroundings may form [30, 31]. When  $r$  is small,  
 360 the minimum fluidisation velocities change sharply with  $x$  and so as segregation  
 361 takes place, the gas velocity necessary to fluidise a region can markedly change.  
 362 The minimum fluidisation velocity measured for a particular bed taken as a  
 363 whole will then often be difficult to predict as its structure would be the result  
 364 of the interaction of several processes that depend on local conditions. Segreg-  
 365 ation makes experimental validation of  $u_{mf2}$  difficult to do for most particle  
 366 mixtures, and may account for the large errors previously encountered when ex-  
 367 pressions for  $u_{mf}$  are compared with experimental data. However, the criteria  
 368 described here for predicting minimum fluidisation velocities can be applied  
 369 to any region within a segregated bed that is uniformly well mixed, and they

may be used to predict their formation and the development of segregation in different mixtures of particles.

The influence of inertia on the minimum fluidisation velocities can be characterised by  $Ar_{av}$ . This has an advantage over using  $Re$  in that it requires only the particles' properties for its calculation. Inertia becomes significant when  $Ar_{av}$  has a value of a few hundred, which means that for many practical beds the effects of inertia are not large; however, when they do become significant, they increase rapidly with increasing diameter.

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## Nomenclature

### *Roman letters*

$Ar$  Archimedes number defined by Eqn (6) [-]

$d$  Particle diameter [m]

$F$  Correction for drag for the presence of other particles [-]

$F_v$  Viscous correction for drag for the presence of other particles [-]

$F_{Re}$  Inertial correction for drag for the presence of other particles [-]

$F_p$  Correction to drag to take into account hydraulic radius for flow around a particular particle [-]

$r$  Ratio of diameters of small to large particles [-]

$Re$  Particle Reynolds number [-]

$u_g$  Superficial gas velocity [m/s]

$u_{mf1}$  Initial minimum fluidisation gas velocity [m/s]



396	$u_{mf2}$	Complete minimum fluidisation gas velocity [m/s]
397	$u_{mf1}^*$	Non-dimensional initial minimum fluidisation gas velocity [-]
398	$u_{mf1}^*$	Non-dimensional complete minimum fluidisation gas velocity [-]
399	$u_t$	Terminal speed for an isolated particle [m/s]
400	$w$	Ratio of density of small to large particles [-]
401	$x$	Mass fraction of small particles [-]
402	$X$	Partial volume fraction of small particles [-]
403	$y$	Ratio of diameter of one component to the average particle diameter [-]
404	$z$	Ratio of density of one component to the average particle density [-]
405	<i>Greek letters</i>	
406	$\mu$	Fluid viscosity [kg/m s]
407	$\rho$	Density [kg/m <sup>3</sup> ]
408	$\phi$	Particle volume fraction
409	<i>Subscripts</i>	
410	0	Value for particles in a mono-sized bed
411	$av$	Average particle
412	$g$	Gas
413	$i$	Either component of the mixture
414	$l$	Large particles
415	$s$	Small particles

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505 **Figure captions**

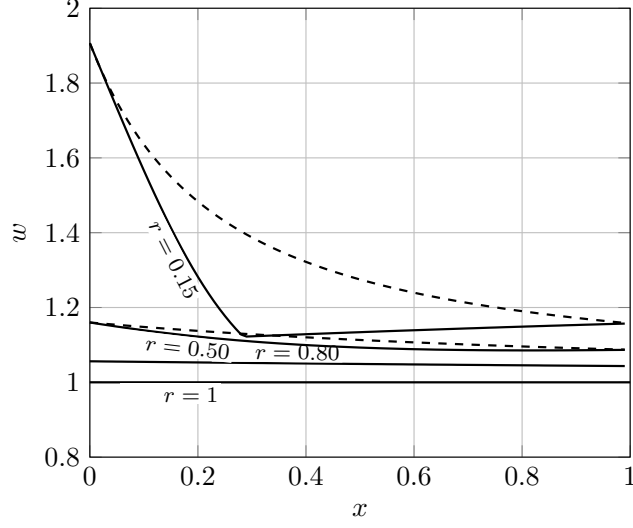


Figure 1: Figure showing the conditions when the force balance on a representative particle for the less-dense component defines  $u_{mf2}$  for a bi-disperse bed. This only happens when  $w > 1$ , but also has a value that lies below the appropriate solid line in the figure. The solid lines take into account packing and the dashed lines represent the curves for fixed  $\phi = \phi_0 = 0.60$ , where this is different.

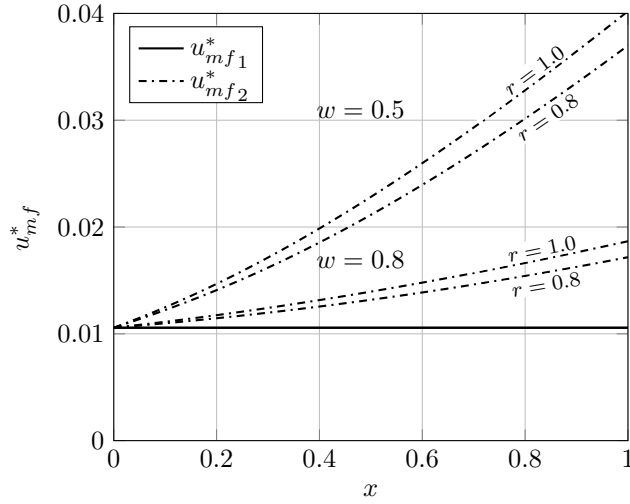
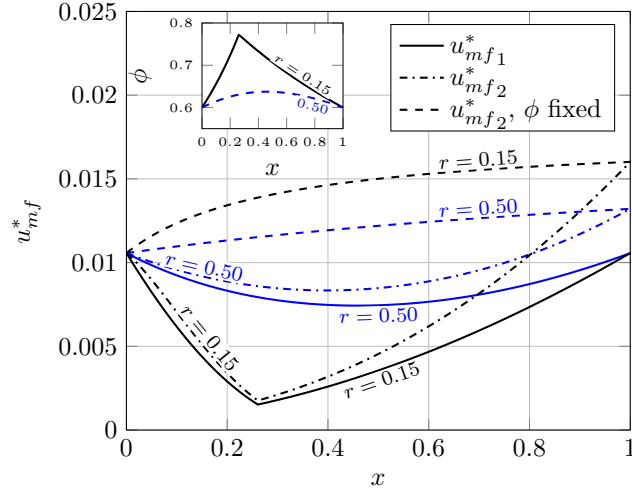
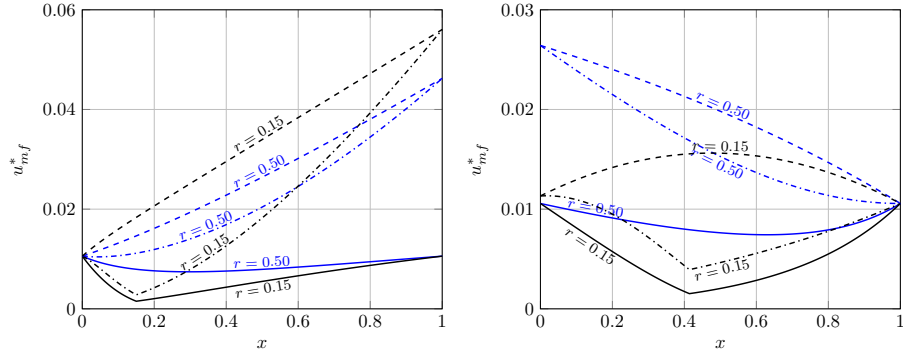


Figure 2: Minimum fluidisation velocities for bi-disperse mixtures for which  $r > 0.74$  and  $\phi = \phi_0$ , and viscous drag dominates. For the case shown  $w < 1$  and  $\phi = \phi_0 = 0.60$ .



(a)  $w = 1$  i.e. both components have the same density. The inset shows the computed variation in  $\phi$  with  $x$ .



(b)  $w = 0.5$  i.e. the larger particles are also denser. (c)  $w = 2$  i.e. the smaller particles are also the denser.

Figure 3: The effects of particle packing on the scaled minimum fluidisation velocities.  $\phi = \phi(x)$ . In all cases inertial effects are negligible and neglected.



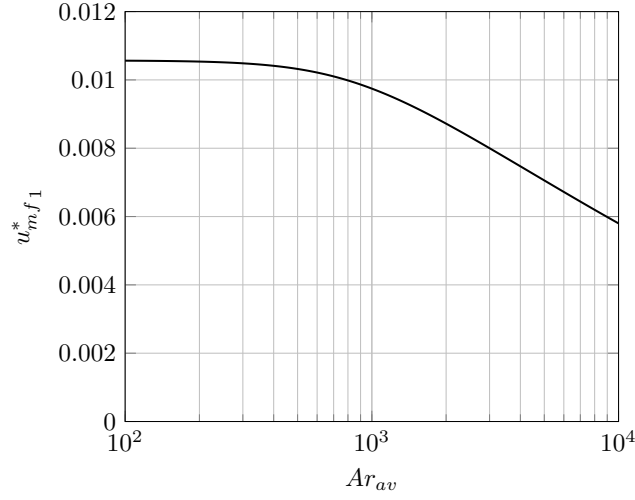


Figure 4: The effect of inertia, characterised with the Archimedes number  $Ar$ , on the scaled minimum fluidisation velocity for the whole bed,  $u_{mf1}^*$ .  $r > 0.74$  so  $\phi = \phi_0$ .  $Ar_{av} = 100$  corresponds to  $Re_{u_{mf1}} = 1.1$ ;  $Ar_{av} = 10\,000$  corresponds to  $Re_{u_{mf1}} = 58$ .  $\phi_0 = 0.60$ .

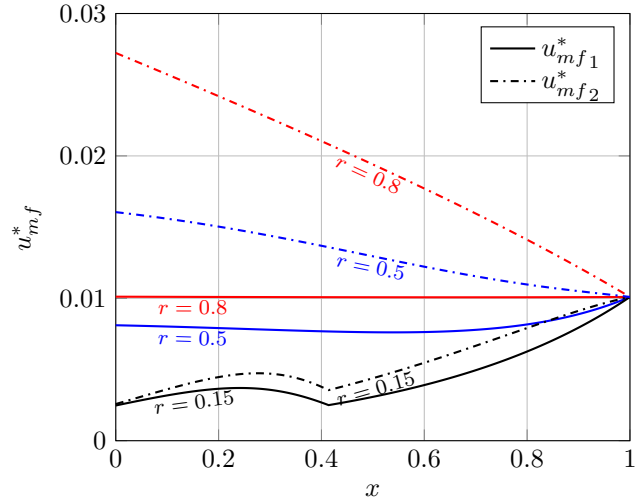
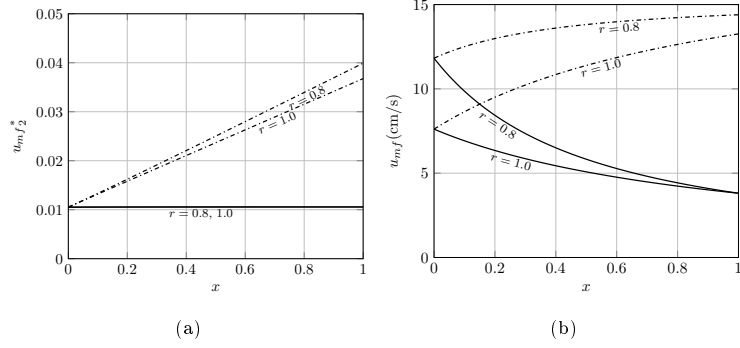
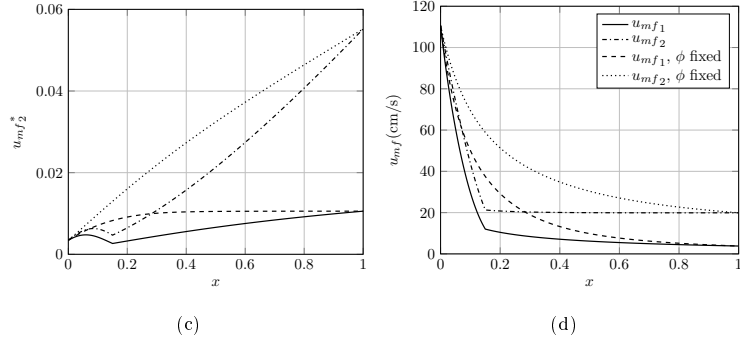


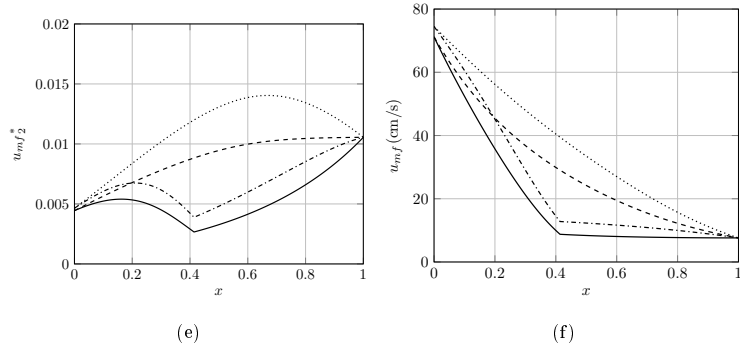
Figure 5: The effect of inertia on scaled minimum fluidisation velocities. For the smaller particles,  $Ar_s = 707$ , which means that inertial effects are important for all  $x$ .  $w = 2$ .



$\rho_s = 1250 \text{ kg/m}^3$ ,  $w = 0.5$ ,  $r = 0.8$  and  $r = 1.0$ .

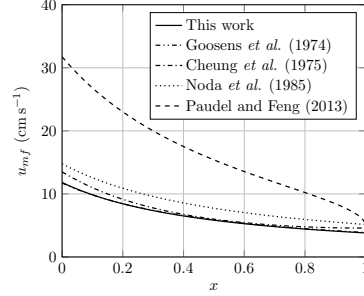


$\rho_s = 1250 \text{ kg/m}^3$ ,  $w = 0.5$ , and  $r = 0.15$ .

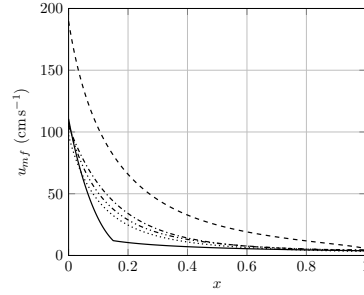


$\rho_s = 2500 \text{ kg/m}^3$ ,  $w = 2$ , and  $r = 0.15$ .

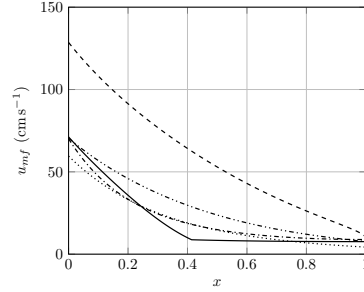
Figure 6: Comparison between scaled (a, c, e) and unscaled (b, d, f) minimum fluidisation velocities for sets of particle properties detailed in Tab. 1. The effects of inertial forces are included in the calculation of the minimum fluidisation velocities.



(a)  $\rho_s = 1250 \text{ kg/m}^3$ ,  $w = 0.5$ ,  $r = 0.8$  and  $r = 1.0$ .



(b)  $\rho_s = 1250 \text{ kg/m}^3$ ,  $w = 0.5$ , and  $r = 0.15$ .



(c)  $\rho_s = 2500 \text{ kg/m}^3$ ,  $w = 2$ , and  $r = 0.15$ .

Figure 7: Comparison between various predictions of bed minimum fluidisation velocity  $u_{mf_1}$  for the sets of particle properties detailed in Tab. 1. Cheung *et al.*[3] is an empirical fit for which the minimum fluidisation velocities for when  $x = 0$  and  $x = 1$  were calculated using the Ergun equation and Goossens *et al.* [4] is the application of the Wen and Yu equation with mixture quantities. Noda *et al.* [6] and Paudel *et al.*[8] are modifications of the Goossens *et al.* approach with fitted changes to the numerical terms in the equation for biomass systems.



Figures	$w$	$r$	$d_s(\mu\text{m})$	$d_l(\mu\text{m})$	$\rho_s(\text{kg/m}^3)$	$\rho_l(\text{kg/m}^3)$	$Ar_s$	$Ar_l$
Figs 6a, 6b	0.5	0.8	300	375	1250	2500	76	298
Fig. 6a, 6b, 7a	0.5	1	300	300	1250	2500	76	153
Fig. 6c, 6d, 7b	0.5	0.15	300	2000	1250	2500	76	45 300
Fig 6e, 6f, 7c	2	0.15	300	2000	2500	1250	153	22 600

Table 1: Table of properties for the particles used in the unscaled examples shown in Figs 6 and 7